# A speed preserving Hilbert gradient flow for generalized integral Menger curvature

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Figure 1: Numerical version of a gradient flow for int $M^{(2.6\overline{3},2)}$ 

**1. Generalized Integral Menger Curvature** [Blatt, Reiter 2015]

generalized integral Menger curvature The  $\operatorname{int} M^{(p,q)}(\gamma)$  is defined as

 $|\gamma'(u_1)| |\gamma'(u_2)| |\gamma'(u_3)| du_1 du_2 du_3$ 

3. Controlling Bi-Lipschitz Constant and Semi-norm via  $int M^{(p,q)}$ 

For curves parametrized by arc-length, Blatt and Reiter give estimates for both quantities. We have, for non-decreasing  $\lambda, \mu : [0, \infty) \to [0, \infty)$ , that

 $\mathfrak{S}$  is Fréchet differentiable and  $D\mathfrak{S}$  is locally Lipschitz continuous.

Also,  $D\mathfrak{S}(\gamma)$  is surjective with right inverse  $R_{\gamma}$  and

$$\|D\mathfrak{S}(\gamma)\|, \|R_{\gamma}\|, L_{D\mathfrak{S}}(\gamma) \leq C\left([\gamma'], \frac{1}{\operatorname{BiLip}(\gamma)}\right),$$

where C is non-decreasing in its components.

7. Minimal Existence Time for the Projected

 $\int\!\!\int\!\!\int_{(\mathbb{R}/\mathbb{Z})^3} \overline{R^{(p,q)}\left(\gamma(u_1),\gamma(u_2),\gamma(u_3)
ight)}$ 

where

$$R^{(p,q)}(x,y,z) := \frac{\left(|z-x| |y-x| |z-y|\right)^p}{\left|(z-x) \wedge (y-x)\right|^q}.$$



**Figure 2:** 
$$R^{(1,1)}$$
 is simply the diameter of the unique circle through  $x, y$  and  $z$ .

We have that  $intM^{(p,p)} = 2^p \mathcal{M}_p$ , the integral Menger curvature.

For injective curves  $\gamma \in C^1(\mathbb{R}/\mathbb{Z},\mathbb{R}^n)$  parametrized by arc-length,

$$\operatorname{int} \mathcal{M}^{(p,q)}(\gamma) < \infty \quad \Leftrightarrow \quad \gamma \in W^{\frac{3p-2}{q}-1,q}(\mathbb{R}/\mathbb{Z},\mathbb{R}^n)$$

with q > 1,  $p \in \left(\frac{2}{3}q+1, q+\frac{2}{3}\right)$ . We work in the Hilbert space setting q = 2, requiring  $p \in \left(\frac{7}{3}, \frac{8}{3}\right)$ .

#### **2. Existence Times for the Gradient Flow**

We want existence of the gradient flow, i.e. a solution to

$$\frac{d}{dt}\gamma(\cdot,t) = -\nabla \operatorname{intM}^{(p,2)}(\gamma(\cdot,t))$$

 $\frac{1}{\operatorname{BiLip}(\gamma)} \le \mu(\operatorname{intM}^{(p,2)}(\gamma))$ 

## $[\gamma'] \le \lambda(\mathrm{int}\mathrm{M}^{(p,2)}(\gamma)).$

and

We can extend these estimates to curves that have a fixed parametrization. Thus, if we have a flow that preserves parametrization, we can find a uniform lower bound for the existence time of each new flow starting at the end of the last one. This would mean that we have long time existence.

### 4. Preserving Constraints via Projected **Gradients** [Neuberger 1997]

Consider Hilbert spaces  $\mathcal{H}_1$ ,  $\mathcal{H}_2$ , an open set  $U \subseteq$  $\mathcal{H}_1$  and two Fréchet differentiable maps  $E: U \rightarrow U$  $\mathbb{R}$ , the energy, and  $\mathfrak{S} : U \to \mathcal{H}_2$ , the constraint. Let  $P_{\mathcal{N}(A)}$  denote the orthogonal projection onto the null-space of an operator A. Assuming a classical solution to

$$\begin{aligned} \frac{d}{dt} u(t) &= -\nabla_{\mathfrak{S}} E(u(t)) \\ &:= -P_{\mathcal{N}(D\mathfrak{S}(u(t)))} \nabla E(u(t)) \end{aligned}$$

exists on [0, T], we have

 $\mathfrak{S}(u(t)) = \mathfrak{S}(u(0))$ 

for all  $t \in [0, T]$ .

## 5. Local Lipschitz Continuity of the **Projected Gradient**

If the constraint is  $C_{loc}^{1,1}$  with pointwise surjective differential, the right hand side is locally Lipschitz and the flow starting at  $x_0 \in U$  exists at least up to time

# **Gradient Flow**

There is a unique classical solution to

$$\frac{d}{dt}\gamma(\cdot,t) = -\nabla_{\mathfrak{S}} \operatorname{int} \mathcal{M}^{(p,2)}(\gamma(\cdot,t))$$
  
$$\gamma(\cdot,0) = \gamma_0 \in W^{\frac{3}{2}p-2,2}_{\operatorname{ir}}(\mathbb{R}/\mathbb{Z},\mathbb{R}^3)$$
(\*)

up to time

$$T = T\left(\left[\gamma_0'\right], \frac{1}{\operatorname{BiLip}(\gamma_0)}\right) > 0.$$

T is non-increasing in its components. With the estimates by Blatt and Reiter, we may instead use the lower bound

$$T = T(\operatorname{intM}^{(p,2)}(\gamma_0))$$

which is non-increasing.

8. Continuing the Flow

Since

$$\frac{d}{dt}\operatorname{int} \mathcal{M}^{(p,2)}(\gamma(\cdot,t)) \le 0,$$

we can restart the flow at time  $T_0$  :=  $T(int M^{(p,2)}(\gamma_0))$ . This yields a new existence time  $T(int M^{(p,2)}(\gamma(\cdot, T_0)))$  which is at least as long as  $T_0$  itself. Iterating this argument yields long time existence.

9. Main Theorem: Long Time Existence

There is a unique classical solution to (\*) which exists for all positive times. We have that

 $(t \mapsto \gamma(\cdot, t)) \in C^{1,1}\left([0, \infty), W^{\frac{3}{2}p-2,2}(\mathbb{R}/\mathbb{Z}, \mathbb{R}^3)\right)$ 



the index ir meaning injective curves which are regular, i.e.  $|\gamma'_0(\cdot)| \ge c > 0$ . The right hand side is locally Lipschitz continuous and we have bounds for both it and the radius of the balls where Lipschitz continuity holds. With these bounds, we obtain a minimal existence time which depends nonincreasingly on

$$\frac{1}{\operatorname{BiLip}(\gamma_0)} := \sup_{x,y \in \mathbb{R}/\mathbb{Z}} \frac{|x-y|_{\mathbb{R}/\mathbb{Z}}}{|\gamma_0(x) - \gamma_0(y)|}$$

and the Gagliardo-semi-norm

 $[\gamma'_0] := [\gamma'_0]_{W^{\frac{3}{2}p-2,2}(\mathbb{R}/\mathbb{Z},\mathbb{R}^3)}.$ 

### $T(M(x_0), \|D\mathfrak{S}(x_0)\|, \|R_{x_0}\|, L_{D\mathfrak{S}}(x_0), r_{\nabla E}(x_0)),$

where  $R_{x_0}$  is a right-inverse to  $D\mathfrak{S}(x_0)$ ,  $L_{D\mathfrak{S}}$  is the Lipschitz constant of  $D\mathfrak{S}$  and  $M(x_0)$  and  $r_{\nabla E}(x_0)$ are an upper bound and a Lipschitz radius for  $\nabla E$ . T is non-decreasing in its last argument and nonincreasing in all the others.

6. A Constraint that Preserves the Parametrization [Scholtes, Schumacher, Wardetzky 2019]

We define  $\mathfrak{S}$  as the logarithmic strain:

$$\mathfrak{S}: W^{\frac{3}{2}p-2,2}_{\mathrm{ir}}(\mathbb{R}/\mathbb{Z},\mathbb{R}^3) \to W^{\frac{3}{2}p-3,2}(\mathbb{R}/\mathbb{Z},\mathbb{R}),$$
$$\gamma \mapsto \ln(|\gamma'(\cdot)|)$$

and, for all  $t \ge 0$ ,  $\left|\frac{d}{dx}\gamma(x,t)\right| = \left|\frac{d}{dx}\gamma_0(x)\right|.$ 

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